

David Sidrane

From: David Sidrane [david_s5@usa.net]
Sent: Monday, February 10, 2014 8:51 AM
To: 'zachary@spark.io'
Cc: 'Zach@Spark.io'
Subject: status and a written walk through

Hi Zachary,

Great speaking with the other today!

Below this you will find status and a written walk through with code annotation.

I have been testing auclnactivity of 0 with a timeout of 8S for connect and 20 S for all other net ops it is working well for more than 3 days!

It also had code to restart the CC3000 on CFOD detection.

It would be good to have it tested by you guys on the network that causes CFOD regularly.

Bin can be found here: http://nscdg.com/spark/0_inact_20_sec_recovery_log_core-firmware.zip

It Has recovery code in it to detect the CFOD and does a reconnect in about 20 second total.

I have ran it for over 72 hours with no issues (hangs or faults) and recovers from network issues in 20 seconds.!

It will Log CFOD;s as

```
0000164364: void SPARK_WLAN_Loop() (582):Resetting CC3000 due to 2 failed connect attempts
```

The test will send a udp packet every 60 seconds to 10.10.0.1 and also does an http get of a lot (3880+ bytes) of data from nscdg.com

Log data goes to Serial1 (3.3V tx,rx pins)

All the log data is critical, because the faults are logged after being detected and mitigated so they do not sent the CPU into a hardfault. Please send the logs and LED observations. (if it dies in a red ...---... Blink N ...---...)

```
1(Faults,RGB_COLOR_RED,HardFault) 12 (Faults,RGB_COLOR_RED,NMIFault)
3 (Faults,RGB_COLOR_RED,MemManage)4 (Faults,RGB_COLOR_RED,BusFault)
5 (Faults,RGB_COLOR_RED,UsageFault)
6 (Cloud,RGB_COLOR_RED,InvalidLenth)
7 (System,RGB_COLOR_RED,Exit)
8 (System,RGB_COLOR_RED,OutOfHeap)
9 (System,RGB_COLOR_RED,SPIOverRun)
10 (Softare,RGB_COLOR_RED,AssertionFailure)11 (Softare,RGB_COLOR_RED,InvalidCase)
```

Status and a written walk through with code annotation is below

Aloha,

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Unsolved:

1. Problem: Socket with inactivity timeout is antithetical to arduino use case of init in setup() use in loop()
2. Problem: Socket of spark protocol is opened by user code and read from spark
The inactivity Timer = 0 seems to fix this!
3. Problem: TI Nvram USER 1 or USER 2 "files" may read back as valid but not necessarily with spark's data set. - Causes connectivity issues.
4. Nuisance: Nice if the project was tied in git to libs. So commits that have lib changes and core changes are tied together. This is the classic one-tree vs 3 trees version control argument. For what it is worth - I prefer all source and third party in 1 tree and tools in a referenced sub tree.

Enhancements:

Added compile time and runtime controlled debugging.

See DEBUG_BUILD and RELEASE_BUILD in make files.

The compile time log level is different. For DEBUG and RELEASE.

```
#if defined(DEBUG_BUILD)
#define LOG_LEVEL_AT_COMPILE_TIME LOG_LEVEL
#define LOG_LEVEL_AT_RUN_TIME LOG_LEVEL // Set to allow all LOG_LEVEL and above messages to be displayed conditionally by levels.
#endif

#if defined(RELEASE_BUILD)
#define LOG_LEVEL_AT_COMPILE_TIME ERROR_LEVEL
#define LOG_LEVEL_AT_RUN_TIME ERROR_LEVEL
#endif
```

To use this feature: compile with DEBUG_BUILD or RELEASE_BUILD

And add this to application.cpp to route the output.

```
void debug_output_(const char *p)
{
  static boolean once = false;
  if (!once)
  {
    once = true;
    Serial1.begin(115200);
  }

  Serial1.print(p);
}
```

(It probably should be a macro) DEFINE_DEBUG(Serial,1)

N.B define USE_ONLY_PANIC To remove **all** but the panic blinker

This adds Debug logging and Panic features.

```
/*
 * This module supports runtime and compile time message filtering.
 *
 * For a message be compiled in the message type has to be >= to then the LOG_LEVEL_AT_COMPILE
 * For a message to be output the message type has to be >= then the LOG_LEVEL_AT_RUN_TIME
 *
 * This module assumes one of two #defines RELEASE_BUILD or DEBUG_BUILD exist
 * Then the LOG_LEVEL_AT_COMPILE_TIME and LOG_LEVEL_AT_RUN_TIME are set based on RELEASE or D
 * For a release build
 *     LOG_LEVEL_AT_COMPILE_TIME = WARN_LEVEL
 *     LOG_LEVEL_AT_RUN_TIME = WARN_LEVEL
 * For a debug build:
 *     LOG_LEVEL_AT_COMPILE_TIME = LOG_LEVEL
 *     LOG_LEVEL_AT_RUN_TIME = LOG_LEVEL
 *
 * The API
 * LOG(fmt,...)
 * DEBUG(fmt,...)
 * WARN(fmt,...)
 * ERROR(fmt,...)
 * PANIC(code,fmt,...)
 */
```

Usage:

define DEBUG_BUILD=y on make command line and add the following to your Application.cpp

```
void debug_output_(const char *p)
{
    static boolean once = false;
    if (!once)
    {
        once = true;
        Serial1.begin(115200);
    }

    Serial1.print(p);
}

The API looks like

LOG("Want %d more cores",count);
WARN("Running %s on cores only %d more left",,"Low",count);
DEBUG("connection closed %d",retValue);
ERROR("Flash write Failed @0x%0x",badd_address);
PANIC(HardFault,"Hit Hardfault");
```

Panic codes are defined in panic_codes.h

Added Panic with SOS on LED.
This is SW magic (or better living through macros :) ,

To use just add a line to panic_codes.h

```

// Add a panic code def_panic_codes(_class, len, code)
// the panic module will send SOS followed by 900 ms delay
// followed by 300 blinks of the value of code
// ... code ...

This is added to the while(1) loop in the code to help identify a Fault or Fault condition
Currently used

def_panic_codes(Faults,RGB_COLOR_RED,HardFault)      1 blink
def_panic_codes(Faults,RGB_COLOR_RED,NPISFault)      2 etc...
def_panic_codes(Faults,RGB_COLOR_RED,MemManage)
def_panic_codes(Faults,RGB_COLOR_RED,BusFault)
def_panic_codes(Faults,RGB_COLOR_RED,UsageFault)

def_panic_codes(Cloud,RGB_COLOR_RED,InvalidLenth)

def_panic_codes(System,RGB_COLOR_RED,Exit)
def_panic_codes(System,RGB_COLOR_RED,OutOfHeap)

```

and the then just use it, no muss, no fuss!

```

void _exit(int status)
{
    PANIC(Exit,"Exit Called");
    while(1);
}

```

Bug fixes and Where:

- 1. Hang in driver on race WIFI_INT (read) v SpiWrite
Solution: was re-write



```

SPARK_Firmware_Driver/src/cc3000_spi.c
//
// We need to prevent here race that can occur in case 2 back to back packets are sent to the
// device, so the state will move to IDLE and once again to not IDLE due to IRQ
//
while (sSpiInformation.ulSpiState != eSPI_STATE_IDLE)
{
}

/* Loop until SPI busy */
while (SPI_I2S_GetFlagStatus(CC3000_SPI, SPI_I2S_FLAG_BSY ) != RESET)
{
}

WIFI_INT (read) ->
while (!tSLInformation.ReadWlanInterruptPin())
{
}

sSpiInformation.ulSpiState = eSPI_STATE_WRITE_IRQ;
sSpiInformation.pTxPacket = pUserBuffer;
sSpiInformation.usTxPacketLength = usLength;

```

This is also wrong and should be a wait while High(H). But only if it was H before the CS asserted. The speed of the proc vs TI sensing CS going low is the only reason there are few hangs here. But run any other ISR that fires at -> below and the code will hang!

```

//
// Assert the CS Line and wait till IRQ line is active and then initialize write operation

```

```

//
ASSERT_CS();  -----
->          -----
while (!tSLInformation.ReadWlanInterruptPin())S/B While high
{
}

//
// Due to the fact that we are currently implementing a blocking situation

```

2. A return from the Callout **SPiRxHandler** from **SpiTriggerRxProcessing** with no call to **SPIResumeSpi()** This happened on duplicate send() result on a closed socket. The first returned success, the seconds returned failure for the same send()! This left the TI never to be heard from again.

Solution is: Set a flag in **SpiWrite** (`tSLInformation.solicitedResponse`) after the write is committed to and before the IO that results in DMA ISR

Then **hci_unsolicited_event_handler(void)** has been refactored:

```

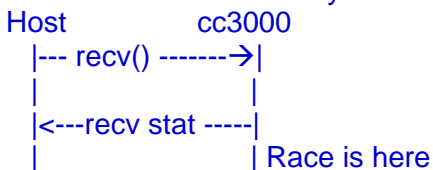
//*****
//
//!! hci_unsolicited_event_handler
//!!
//!! @param None
//!!
//!! @return      ESUCCESS if successful, EFAIL if an error occurred
//!!
//!! @brief      Parse the incoming unsolicited event packets and issues
//!!             corresponding event handler.
//!!
//!!
//*****
long
hci_unsolicited_event_handler(void)
{
    unsigned long    res = 0;
    int isEvent = 0;
    unsigned char *pucReceivedData;

    // Buffer has message in it
    if (tSLInformation.usEventOrDataReceived != 0)
    {
        pucReceivedData = (tSLInformation.pucReceivedData);
        isEvent = (*pucReceivedData == HCI_TYPE_EVT);
        // An event did hci_unsol_event_handler handle it?
        res = isEvent && hci_unsol_event_handler((char *)pucReceivedData);
    }

    // Handled here Or if not there is no outstanding write (solicitedResponse)
    if (res || (isEvent && tSLInformation.solicitedResponse == 0) ) {
        // There was an unsolicited event received - we can release the buffer
        // and clean the event received
        if (!res)
        {
            ERROR("isEvent w/Opcode ==0  0x%02x 0x%02x 0x%02x 0x%02x 0x%02x 0x%02x 0x%02x 0x%02x 0x%02x 0x%02x",
                pucReceivedData[0],pucReceivedData[1],pucReceivedData[2],pucReceivedData[3],
                pucReceivedData[4],pucReceivedData[5],pucReceivedData[6],pucReceivedData[7],
                pucReceivedData[8],pucReceivedData[9]);
        }
        tSLInformation.usEventOrDataReceived = 0;
        // Fire it up again
        SpiResumeSpi();
    }
    return res;
}

```

3. Ti code over writes memory when Receive is done. The transaction looks like



|<---recv data-----|

```
    if (tSLInformation.usRxDataPending == 0) < fixes race we only return data to the Call that wanted it
    {
        ERROR("type != HCI_TYPE_EVT is (%d) usRxDataPending=%d usRxEventOpcode=%u usReceivedEventOpcode=%u",
            *pucReceivedData,
            tSLInformation.usRxDataPending,
            tSLInformation.usRxEventOpcode,
            usReceivedEventOpcode);
    }
    else
    {
        pucReceivedParams = pucReceivedData;
        STREAM_TO_UINT8((char *)pucReceivedData, HCI_PACKET_ARGSIZE_OFFSET, ucArgsize);

        STREAM_TO_UINT16((char *)pucReceivedData, HCI_PACKET_LENGTH_OFFSET, usLength);

        // Data received: note that the only case where from and from Length
        // are not null is in recv from, so fill the args accordingly
        if (from)
        {
            STREAM_TO_UINT32((char *) (pucReceivedData + HCI_DATA_HEADER_SIZE), BSD_RECV_FROM_FROMLEN_OFFSET, *(unsigned long *)fromlen);
            memcpy(from, (pucReceivedData + HCI_DATA_HEADER_SIZE + BSD_RECV_FROM_FROM_OFFSET), *fromlen);
        }

        // Let's vet Length < This fixes the Bug #4
        long length = usLength - ucArgsize;

        if (length <= 0 || length > arraySize(wlan_rx_buffer))
        {
            // Not sane
            length = -1;
        }
        else
        {
            memcpy(pRetParams, pucReceivedParams + HCI_DATA_HEADER_SIZE + ucArgsize, length);
        }

        // fixes the Nvram read not returning Length
        if (fromlen)
        {
            *fromlen = length; < This fixes the nvram API Bug #5
        }

        tSLInformation.usRxDataPending = 0;
    }

    tSLInformation.usEventOrDataReceived = 0;

    SpiResumeSpi(); < if the cc3000 has reinterrupted the second ISR will hit here

    // Since we are going to TX - we need to handle this event after the
    // ResumeSpi since we need interrupts
    if ((*pucReceivedData == HCI_TYPE_EVT) && (usReceivedEventOpcode == HCI_EVT_PATCHES_REQ))
    {
        hci_undef_handle_patch_request((char *)pucReceivedData);
    }

    if ((tSLInformation.usRxEventOpcode == 0) && (tSLInformation.usRxDataPending == 0))
    {
        break;
    }
}
return NULL;
}
```

4. Memory overwrites memory for odd data from rxed from CC30000 when it is losing it's cookies.
Solution is Above #4

Recived data look like:


```

unsigned char *RetParams;

volatile int32_t start = millis();
while (1)
{
    if (tSLInformation.usEventOrDataReceived == 0)
    {
        volatile int32_t now = millis();
        volatile int32_t elapsed = now - start;
        if (elapsed < 0) { // Did we wrap
            elapsed = start + now; // yes now
        }

        if (cc3000__event_timeout_ms && (elapsed >= cc3000__event_timeout_ms)) < will timeout any
calls

        {
            ERROR("Timeout now %ld start %ld elapsed %ld cc3000__event_timeout_ms
%ld",now,start,elapsed,cc3000__event_timeout_ms);
            ERROR("Timeout waiting on tSLInformation.usRxEventOpcode 0x%04x",tSLInformation.usRxEventOpcode);

            // Timeout Return Error for requested Opcode
            // This sucks because callers should have initialized pucReceivedParams
switch(tSLInformation.usRxEventOpcode) < will return the correct opcode

{

default:
    INVALID_CASE(tSLInformation.usRxEventOpcode);
    break;

case HCI_CMND_SIMPLE_LINK_START:
case HCI_CMND_READ_BUFFER_SIZE:
    break;

case HCI_CMND_WLAN_CONFIGURE_PATCH:
case HCI_NETAPP_DHCP:
case HCI_NETAPP_PING_SEND:
case HCI_NETAPP_PING_STOP:
case HCI_NETAPP_ARP_FLUSH:
case HCI_NETAPP_SET_DEBUG_LEVEL:
case HCI_NETAPP_SET_TIMERS:
case HCI_EVT_NVMEM_READ:
case HCI_EVT_NVMEM_CREATE_ENTRY:
case HCI_CMND_NVMEM_WRITE_PATCH:
case HCI_NETAPP_PING_REPORT:
case HCI_EVT_MDNS_ADVERTISE:
case HCI_EVT_READ_SP_VERSION:
case HCI_EVT_SELECT:
    *(unsigned char *)pRetParams = -1;
    break;

case HCI_CMND_SETSOCKOPT:
case HCI_CMND_WLAN_CONNECT:
case HCI_CMND_WLAN_IOCTL_STATUSGET:
case HCI_EVT_WLAN_IOCTL_ADD_PROFILE:
case HCI_CMND_WLAN_IOCTL_DEL_PROFILE:
case HCI_CMND_WLAN_IOCTL_SET_CONNECTION_POLICY:
case HCI_CMND_WLAN_IOCTL_SET_SCANPARAM:
case HCI_CMND_WLAN_IOCTL_SIMPLE_CONFIG_START:
case HCI_CMND_WLAN_IOCTL_SIMPLE_CONFIG_STOP:
case HCI_CMND_WLAN_IOCTL_SIMPLE_CONFIG_SET_PREFIX:
case HCI_CMND_EVENT_MASK:
case HCI_EVT_WLAN_DISCONNECT:
case HCI_EVT_SOCKET:
case HCI_EVT_BIND:
case HCI_CMND_LISTEN:
case HCI_EVT_CLOSE_SOCKET:
case HCI_EVT_CONNECT:
case HCI_EVT_NVMEM_WRITE:
case HCI_EVT_BSD_GETHOSTBYNAME:
    *(int32_t *)pRetParams = -1;
    break;

case HCI_EVT_RECV:
case HCI_EVT_RECVFROM:
case HCI_EVT_ACCEPT:

```



```
case HCI_EVT_SEND:
case HCI_EVT_SENDTO:
case HCI_CMND_GETSOCKOPT:
    *(int32_t *)pRetParams = -1;
    pRetParams += sizeof(int32_t);
    *(int32_t *)pRetParams = -1;
    break;

case HCI_CMND_WLAN_IOCTL_GET_SCAN_RESULTS:
    *(int32_t *)pRetParams = 0;
    break;

case HCI_NETAPP_IPCONFIG:
    memset(pRetParams, 0, sizeof(tNetappIpconfigRetArgs));
    break;
}
break; // Exit Loop
}
}
```